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The second derivative of $f(x)$, for $x = 0$, is given by $f''(x) = 2\sqrt{2} - 2\cos(2\sqrt{3}\ln x) + 4\sqrt{3}\sin(2\sqrt{3}\ln x)$. Thus: $f''(x_k) = 2\sqrt{2} - 2\cos \frac{\pi}{4} + 4\sqrt{3}\sin \frac{\pi}{4} = 2\sqrt{2} - 2\sqrt{2} + 4\sqrt{3}\sqrt{2} = 4\sqrt{6}$. Similarly $f''(y_k) = 2\sqrt{2} - 2\cos -\frac{\pi}{4} + 4\sqrt{3}\sin -\frac{\pi}{4} = 2\sqrt{2} - 2\sqrt{2} - 4\sqrt{3}\sqrt{2} = -4\sqrt{6}$. Hence, $\{x_k \mid k \geq 0\}$ is a sequence of nonsingular local minima, which evidently converges to x^* ,

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1.2. Linear Programming: A Graphical
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is shown in Figure 1.4. The LP has
alternative optimal solutions that fall on
the segment connecting $x = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ to $x = \begin{bmatrix} 6 \\ 0 \end{bmatrix}$. Each such solution has an
objective value of $z = 12$, and the
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segment is given by $x = \frac{3t+6(1-t)}{t+0(1-t)}$...

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assumptions or approximations may also
lead to appropriate problem
representations over the range of
decision variables being considered. At
other times,

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